Siddhartha Banerjee

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EDUCATION

GEORGIA INST. OF TECH.

PH.D. IN ROBOTICS May 2021 | Atlanta, GA Advised by Dr. Sonia Chernova

YALE UNIVERSITY

B.S. IN ELECTRICAL

ENGINEERING/COMPUTER SCIENCE May 2013 | New Haven, CT Distinction in Major GPA: 3.7/4.0

VASANT VALLEY SCHOOL

Grad. 2009 | New Delhi, India

LINKS

Github:// banerjs LinkedIn:// banerjs Goodreads:// siddhartha-banerjee

COURSEWORK

GRADUATE

Artificial Intelligence (Student & TA) Deep Learning Linear Systems & Control Nonlinear Systems Human-Robot Interaction (Student & TA) Human-Computer Interaction Evaluation of Human Integrated Systems

UNDERGRADUATE

Intro to VLSI System Design Systems & Control Science of Complex Systems Systems Programming Design & Analysis of Algorithms Intelligent Robotics Computational Vision Database Systems Mobile Computing & Wireless Networks

PROGRAMMING

LANGUAGES

Familiar: Python • C++ • C • Java • C# MATLAB • Shell • Javascript R • SQL • LATEX

FRAMEWORKS

ROS • Django • React • PyTorch

WORK EXPERIENCE

DILIGENT ROBOTICS | ROBOTICS SOFTWARE ENGINEER

May 2018 - August 2018, January 2021 - Current | Austin, TX

- Developing behaviours for Moxi, the robot, and capabilities in backend services
- Lead for Remote Operations

MICROSOFT | RESEARCH INTERN

May 2017 - August 2017 | Seattle, WA

- Worked with Situated Interaction Group
- Setup a robot for in-the-wild activity recognition, with a focus on learning from human-robot interaction

REDFIN | SOFTWARE ENGINEER

July 2013 – June 2015 | Seattle, WA

- Designed and maintained ETL pipeline for house listing data
- Integrated 3rd party GIS data
- Calculated and displayed aggregate housing data for regions
- Maintained internal tools for managing agents and locations

AWARDS & LEADERSHIP

2019 Panel Chair 2017–2018 President 2014 Employee of Quarter 2011 Fellow

2011-2012 Vice-President

2007 Winner

Georgia Tech RoboGrads Redfin Yale Entrepreneurial Institute Summer Fellowship Yale Formula Hybrid FSAE Team Indian Robot Olympiad

HRI Pioneers Workshop

NOTABLE PUBLICATIONS

- S. Banerjee, A. Silva, and S. Chernova, "Robot classification of human interruptibility and a study of its effects," ACM Trans. on Human-Robot Interaction (THRI), vol. 7, no. 2, p. 14, 2018.
- [2] D. Das, S. Banerjee, and S. Chernova, "Explainable ai for robot failures: Generating explanations that improve user assistance in fault recovery," in *Proc. Int. Conf. on Human-Robot Interaction (HRI)*. New York, NY, USA: Association for Computing Machinery, 2021, p. 351–360.

SELECT PROJECTS

FETCHIT! CHALLENGE | ROBOTICS COMPETITION Summer 2019 | ICRA

Developed robot software to complete a mobile manipulation challenge at the ICRA 2019 FetchIt! Challenge hosted by Fetch Robotics. The team placed first, winning a Fetch mobile manipulator robot.

YALE FORMULA HYBRID FSAE | STUDENT ORGANIZATION

2009 - 2013 | Yale

Designed and built formula style gas-electric hybrid cars to compete nationally. Team won several awards including Best Hybrid Car (2013), Ford Efficiency (2013), Chrysler Innovation (2013), & GM Best Engineered Hybrid System (2010, 2013)